| • | Four Independent Drivers and Receivers                              |
|---|---|
| • | Loopback Mode Functionally Self Tests Drivers and Receivers Without |
|   | Disconnection From Line   |
| • | Driver Slew Rate Controlled by a Single Resistor                    |
| • | Internal Thermal-Overload Protection                                |

- RS-423-B Inputs and Outputs Designed to Withstand ±25 V
- **ESD Protection Exceeds 2000 V Per** MIL-STD-833C Method 3015
- **LinBiCMOS™ Process Technology**

### description

The SN75LBC786 is a monolithic quadruple RS-423-B driver and receiver with integratedloopback function. The operation of the

**DW PACKAGE** (TOP VIEW) 28 7 2LB ЗА 3Z **∏** 2 27 1 2Z 3LB 🛮 3 26 2A 25 1LB 4A [ 4Z 🛚 24**∏** 1Z 5 4LB ∏ 6 23 П 1А 22 R<sub>WS</sub> V<sub>SS</sub> [] 7 GND [ 8 21 V<sub>DD</sub> 20**∏** 1Y 4B [ 9 19 🛮 1B 4Y ∏ 10 3B **∏** 11 18 2Y 17 1 2B 3Y [ 12 16 🛮 2C 3C **1** 13 4C **∏** 14 15**∏** 1C

SN75LBC786 is closely based on that of the SN75186. In normal operation, the device performs as four independent RS-423-B driver/receiver pairs designed to interface data-terminal equipment (DTE) with data circuit-terminating equipment (DCE). In loopback mode, the signal from each driver output is fed back via special circuitry into its associated receiver input, removing the need to locally disconnect cables and install a loopback connector. The receiver output signal is the same as the driver input signal.

The SN75LBC786 is characterized for operation over the temperature range of 0°C to 70°C.

#### **FUNCTION TABLE**

| LOOPBACK    | II.         | NPUTS       | OUT              | PUTS             |                  |
|-------------|-------------|-------------|------------------|------------------|------------------|
| LB          | Α           | В           | С                | Z                | Υ                |
| нтт         | LILI        | L<br>L<br>H | H<br>H<br>L<br>L | HHLL             | H<br>L<br>H<br>L |
| H<br>H<br>H | L<br>H<br>L | L<br>L<br>H | L<br>L<br>H      | ?<br>?<br>?<br>? | H<br>L<br>H<br>L |
| L<br>L      | L<br>H      | X<br>X      | X<br>X           | L<br>H           | L<br>L           |

H = high level, L = low level, X = irrelevant, ? = indeterminate

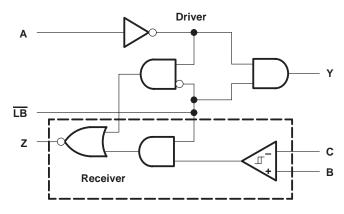


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### logic diagram (positive logic) (each transceiver)



### absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

| Positive supply voltage, V <sub>DD</sub> (see Note 1)            |                       |
|--|-----------------------|
| Negative supply voltage, V <sub>SS</sub>                         | 14 V                  |
| Receiver input voltage range                                     | –30 V to 30 V         |
| Driver input voltage range                                       | 0.5 V to 5.75 V       |
| Loopback input voltage range                                     | 0.5 V to 5.75 V       |
| Driver output voltage range (supplies at 0 V)                    | $\dots$ -30 V to 30 V |
| Driver output voltage range (supplies at ±12 V)                  | –25 V to 25 V         |
| Continuous power dissipation at (or below) T <sub>A</sub> = 70°C | 800 mW                |
| Operating free-air temperature range, T <sub>A</sub>             | 0°C to 70°C           |
| Storage temperature range, T <sub>stq</sub>                      | 65°C to 150°C         |
| Case temperature for 10 seconds                                  |                       |

<sup>†</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTE 1: All voltages are with respect to network ground terminal.

### recommended operating conditions

|  |                     | MIN   | NOM | MAX   | UNIT |
|--|---------------------|-------|-----|-------|------|
| Supply voltage, V <sub>DD</sub>          |                     | 10.8  | 12  | 13.2  | V    |
| Supply voltage, V <sub>SS</sub>          |                     | -10.8 | -12 | -13.2 | V    |
| High-level input voltage, VIH            | Driver and loopback | 2     |     |       | V    |
| Low-level input voltage, V <sub>IL</sub> | Driver and loopback |       |     | 0.8   | V    |
| High-level output current, IOH           | Receiver            |       |     | -4    | mA   |
| Low-level output current, IOL            | Receiver            |       |     | 4     | mA   |
| Slew rate control resistor, RWS          |                     | 20    | 82  | 820   | kΩ   |
| Operating free-air temperature, TA       |                     | 0     |     | 70    | °C   |



### **DRIVER SECTION**

## electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

|   | PARAMETER                                  |   | DITIONS               | MIN  | TYP  | MAX | UNIT |
|---|--|---|-----------------------|------|------|-----|------|
| Vон   | High-level output voltage                  | Open circuit or RI =                    | 450 Ω                 | 4    | 5.5  | 6   | V    |
| VOL   | Low-level output voltage                   | Open circuit or RI =                    | 450 Ω                 | -6   | -5.5 | -4  | V    |
| Iн  | High-level input current                   | $V_{I} = 2.4 \text{ V} - 5.5 \text{ V}$ |                       |      |      | 100 | μА   |
| I <sub>Ι</sub> L                                | Low-level input current                    | V <sub>I</sub> = 0 V - 0.8 V            |                       | -100 |      |     | μΑ   |
| likg  | Output leakage current                     | $V_{DD} = V_{SS} = 0 V$                 | V <sub>O</sub> = ±6 V | -100 |      | 100 | μΑ   |
| IOS(H)  | High-level short-circuit output current    | V <sub>I</sub> = high,                  | VO = 0 V              | 15   |      | 45  | mA   |
| IOS(L)  | Low-level short-circuit output current     | $V_I = low,$                            | VO = 0 V              | -45  |      | -15 | mA   |
|   | Complete company (learning of eff)         | No load,                                | LB at 2 V             |      | 10   | 12  | Λ    |
| IDD   | Supply current (loopback off)              | $RI = 450 \Omega$ ,                     | LB at 2 V             |      | 60   | 70  | mA   |
| I <sub>DD(LB)</sub>                             | Supply current with loopback on            | No load,                                | LB at 0.8 V           |      | 13   | 16  | mA   |
|   | Owner to compact (I a contract of the off) | No load,                                | LB at 2 V             |      | -10  | -12 | A    |
| Iss   | Supply current (loopback off)              | $RI = 450 \Omega$ ,                     | LB at 2 V             |      | -60  | -70 | mA   |
| I <sub>DD</sub> Supply current with loopback on |  | No load,                                | LB at 0.8 V           |      | -13  | -16 | mA   |
| LOOPBA  | CK MODE                                    |   |                       | -    |      |     |      |
|   | Output voltage (input either high or low)  | $RI = >450 \Omega$ ,                    | V <sub>LB</sub> = low | -6   | -5.5 | -4  | V    |

# switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

|                 | PARAMETER  | 1              | TEST CONDITI                   | ONS                            | MIN | TYP | MAX | UNIT |
|-----------------|--|----------------|--------------------------------|--------------------------------|-----|-----|-----|------|
|                 |  |                |                                | $R_{WS} = 0 k\Omega$           |     | 1.5 |     |      |
|                 |  |                |                                | $R_{WS} = 20 \text{ k}\Omega$  | 1.5 | 2.1 | 2.7 |      |
| tTLH            | Transition time, low-to-high level output (see Figure 1) |                | $RI = 450 Ω$ , $C_L = 50 pF$ , | $R_{WS} = 82 \text{ k}\Omega$  | 5   | 8   | 11  | μs   |
|                 | (See Figure 1)   |                |                                | $R_{WS} = 820 \text{ k}\Omega$ |     | 80  |     |      |
|                 |  | RI = 450 Ω,    |                                | $R_{WS} = 0 k\Omega$           |     | 1.5 |     |      |
|                 |  | $V_{WS} = 5 V$ |                                | $R_{WS} = 20 \text{ k}\Omega$  | 1.5 | 2.1 | 2.7 |      |
| tTHL            | Transition time, high-to-low level output (see Figure 1) |                |                                | $R_{WS} = 82 \text{ k}\Omega$  | 5   | 8   | 11  | μs   |
|                 | (See Figure 1)   |                |                                | $R_{WS} = 820 \text{ k}\Omega$ |     | 80  |     |      |
| SR              | Output slew rate   |                |                                | $R_{WS} = 20 \text{ k}\Omega$  |     |     | 15  | V/µs |
| t <sub>sk</sub> | Output skew,  tpHL - tpLH  (see Figure 4)                |                |                                | $R_{WS} = 82 \text{ k}\Omega$  |     |     | 1   | μs   |

### RECEIVER SECTION

### electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

|                  | PARAMETER                               | TEST CO  | NDITIONS             | MIN   | TYP  | MAX  | UNIT |
|------------------|---|--|----------------------|-------|------|------|------|
| \/:-             | Receiver input threshold voltage        | $\forall_{IT} = (\forall_{I+} - \forall_{I-})$ |                      | -200  |      | 200  | mV   |
| VIT              | (see Figure 5)                          | $V_{IT} = (V_{I+} - V_{I-})$ with 50           | 00-Ω series resistor | -400  |      | 400  | IIIV |
| 1.               | Input current                           | V <sub>I</sub> = 10 V                          | Other input to GND   |       | 1.3  | 3.25 | mA   |
| ''               | input current                           | V <sub>I</sub> = -10 V                         | Other input to GND   | -3.25 | -1.3 |      | IIIA |
| V <sub>hys</sub> | Hysteresis voltage                      |  |                      | 20    | 40   | 150  | mV   |
| \/               | High-level output voltage (see Note 2)  | $I_{O} = -20 \mu\text{A}$                      |                      | 3.5   |      | 5    | V    |
| VOH              | nigri-level output voltage (see Note 2) | $I_O = -4 \text{ mA}$                          |                      | 2.4   |      | 5    | V    |
| VOL              | Low-level output voltage                | $I_O = 20 \mu A \text{ to 4 mA}$               |                      |       |      | 0.4  | V    |
| los              | RX short circuit current                |  |                      |       |      | 50   | mA   |
| $V_{\text{ID}}$  | Differential input voltage              | Receiver inputs open cir                       | cuit                 | 1.6   | 2.1  | 2.6  | V    |
| Vofs             | Fail safe output voltage                | See Note 3                                     |                      | 3.5   |      |      | V    |

NOTES: 2. Device has an internal RX supply regulator. Maximum RX logic output voltage under no load is thus defined by an internal voltage value. This is nominally set to 4.5 V with a tolerance of ±5%.

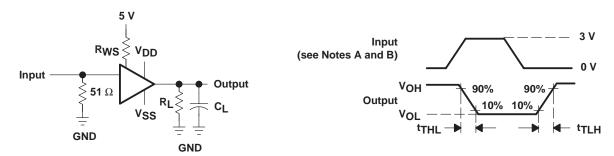
## switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

|                  | PARAMETER  | TEST CONDITIONS | MIN | NOM  | MAX | UNIT |
|------------------|--|-----------------|-----|------|-----|------|
| tPLH             | Propagation delay time, low-to-high (see Figure 2) |                 |     | 0.15 | 4   |      |
| tPHL             | Propagation delay time, high-to-low (see Figure 2) | $C_1 = 50  pF$  |     | 0.15 | 1   | μs   |
| <sup>t</sup> THL | Transition time, high-to-low (see Figure 3)        | OL = 50 pr      |     | 20   | 200 | no   |
| tTLH             | Transition time, low-to-high (see Figure 3)        |                 |     | 20   | 200 | ns   |



<sup>3.</sup> One input at ground, other input open circuit,  $I_O = -20 \mu A$ , or both open circuit.

### PARAMETER MEASUREMENT INFORMATION



NOTES: A.  $C_L$  includes probe and jig capacitance.

B. The input pulse is supplied by a generator having the following characteristics:  $t_r \le 10$  nS,  $t_f < 10$  nS,  $Z_0 = 50$   $\Omega$ , PRR  $\ge 5$  kHz, duty cycle = 50%,  $V_{max} = 3$  V,  $V_{min} = 0$  V.

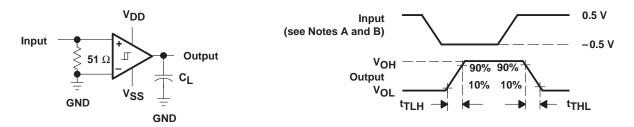
**Figure 1. Driver Transition Times** 



NOTES: A.  $C_L$  includes probe and jig capacitance.

B. The input pulse is supplied by a generator having the following characteristics:  $t_{\Gamma} \le 10$  nS,  $t_{f} < 10$  nS,  $t_{Q} = 50$   $\Omega$ , PRR  $\ge 5$  kHz, duty cycle = 50%,  $t_{Q} = 50$  V,  $t_{Q} = 50$  V,  $t_{Q} = 50$  V.

Figure 2. Receiver Propagation Delay Times

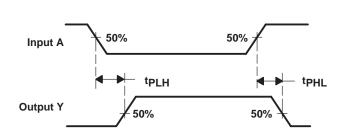


NOTES: A.  $C_L$  includes probe and jig capacitance.

B. The input pulse is supplied by a generator having the following characteristics:  $t_{\Gamma} \le 10$  nS,  $t_{f} < 10$  nS,  $t_{O} = 50$   $\Omega$ , PRR  $\ge 5$  kHz, duty cycle = 50%,  $t_{O} = 50$  V,  $t_{O} = 50$  V.

**Figure 3. Receiver Transition Times** 

### PARAMETER MEASUREMENT INFORMATION



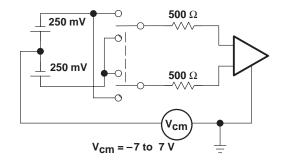


Figure 4. Skew Definition Times

Figure 5. Input Balance Test

### PRINCIPLES OF OPERATION

In normal operation, the SN75LBC786 functions as four independent drivers and receivers. The loopback mode is disabled by maintaining a high logic level on the LB input. The receivers consist of differential comparators with hysteresis and resistive attenuation on the inputs. The resistive attenuation improves the input common-mode range and also provides additional protection from ESD and over-voltage stress. The differential and common-mode input impedance are sufficiently high to meet RS-423-B. The balance of the receiver input voltage current characteristics and bias voltage is such that the receiver remains in the intended binary state when a differential voltage of 500 mV is applied to the inputs through 500  $\Omega$  across the entire common-mode range (see Figure 5).

The drivers meet all RS-423-B specifications. In normal operation, the drivers have built-in current limits and thermal overload protection. Slew-rate controlling circuitry is included into the design that is adjusted to suit the application by means of an external resistor. The slew-rate controlling circuitry also has a default mode. If RWS is shorted to 5 V externally, the transition time defaults to approximately 1.5 μs. The receiver is compatible to the RS-232 with the use of external input resistors to meet the RS-232 input-resistance specification of 3 k $\Omega$  to 7 k $\Omega$ .

Taking an individual  $\overline{LB}$  input low activates the loopback mode in the corresponding driver/receiver pair. This causes the output from that driver to be fed back to the input of its receiver through dedicated internal-loopback circuitry. Data from the receiver output can then be compared, by a communication system, with the data transmitted to the driver to determine if the functional operation of the driver and receiver together is correct.

In the loopback mode, external data at the input of the receiver is ignored and the driver does not transmit data onto the line. Extraneous data is prevented internally from being sent by the driver in the loopback mode by clamping its output to a level below the maximum interface voltage, -5 V, or the EIA-423-B marking state. Below this marking level, a reduced 1.5-V output amplitude is used at the driver output. This signal is detected by an on-chip loopback comparator and fed to the input stage of the receiver to complete the loop.

Line faults external to the SN75LBC786 are detected in addition to device failures. These line faults include short circuits to ground and to external supply voltages. The loopback mode should be entered only when the driver output is low, that is, the marking condition. It is recommended that loopback not be entered when the driver output is in a high state as this may cause a low-level, nondamaging oscillation at the driver output.





### PACKAGE OPTION ADDENDUM

24-Apr-2008

### **PACKAGING INFORMATION**

| Orderable Device | Status <sup>(1)</sup> | Package<br>Type | Package<br>Drawing | Pins | Package<br>Qty | e Eco Plan <sup>(2)</sup> | Lead/Ball Finish | MSL Peak Temp <sup>(3)</sup> |
|------------------|-----------------------|-----------------|--------------------|------|----------------|---------------------------|------------------|------------------------------|
| SN75LBC786DW     | NRND                  | SOIC            | DW                 | 28   | 20             | Green (RoHS & no Sb/Br)   | CU NIPDAU        | Level-1-260C-UNLIM           |
| SN75LBC786DWG4   | NRND                  | SOIC            | DW                 | 28   | 20             | Green (RoHS & no Sb/Br)   | CU NIPDAU        | Level-1-260C-UNLIM           |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

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**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

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(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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